Sample Test Name: Automation and Robotics



(These items were developed by teachers for the Technical Skills Assessment. Below is a sample item for each program standard.)

| Question 1 of 13 |
|--|
| Who is responsible for the death of a human if a teleoperated robot was involved and mechanical design or software failures were NOT identified? |
| A) Designer |
| ○ B) Manufacturer |
| OC) Owner |
| Operator |
| Question 2 of 13 |
| How many connections are REQUIRED between analog ground and digital ground in a single circuit |
| OA) Three |
| OB) None |
| C) Two |
| Op) One |
| Question 3 of 13 |
| What material property has the MOST influence on a robot in transporting a payload? |
| ○ A) Strength |
| OB) Density |
| OC) Luminosity |
| OD) Speed |

| Question 4 | 4 (| of 1 | 13 |
|------------|-----|------|----|
|------------|-----|------|----|

What module is NOT a component of a typical Programmable Logic Controller (PLC)?

- A) Output
- **B)** Animation
- C) Input
- O) Memory

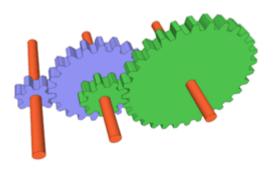
Question 5 of 13

What is the MAIN focus when designing a new system?

- A) Maintenance
- B) Speed
- OC) Safety
- O) Strength

Question 6 of 13

The left rear gear is the input and the right forward gear is the output. What impact does this gear ratio have?



- A) Increase speed
- B) Increase power
- C) Increase torque
- OD) Increase pressure

| Question 7 of 13 | Qu | est | ion | 7 | of | 1 | 3 |
|------------------|----|-----|-----|---|----|---|---|
|------------------|----|-----|-----|---|----|---|---|

Which view gives the BEST representation of an object from all angles?

- A) Side
- B) Geometric
- C) Isometric
- O) Front

Question 8 of 13

What is the mechanical advantage of a robotic arm (lever) that requires an input force of 10 pounds and can lift an object that weighs 40 pounds if using the formula "mechanical advantage equals output force/input force?"

- **A**) 4
- **B**) .4
- **C)** 40
- **D)** 400

Question 9 of 13

What is this connector? (Shared via Google Drive)



- A) Centronics
- B) Parallel
- OC) SCSI
- OD) USB-A

| Question 10 of 13 | | | |
|-------------------|--|--|--|
| What | type of sensor is NOT used to detect force? | | |
| () A) | Strain gauge | | |
| ○ B) | Scale | | |
| (C) | Torque sensor | | |
| (D) | Thermocouple | | |
| Ques | ation 11 of 13 | | |
| What ı | machine is used for subtractive manufacturing? | | |
| () A) | 3D printer | | |
| ○ B) | Injection molding | | |
| () C) | Resin printer | | |
| (D) | CNC | | |
| Ques | stion 12 of 13 | | |
| What i | is the function of a flowchart? | | |
| (A) | Provides a recipe for results | | |
| ○ B) | Illustrates programming language use by robots | | |
| () C) | Illustrates a sequence of movements or actions | | |
| O D) | Provides technical specs | | |
| Ques | stion 13 of 13 | | |
| What a | are examples of safety hardware and circuits? | | |
| (A) | Switches and enable guards | | |
| ○ B) | Movements and speed relays | | |
| () C) | Light curtains and emergency E-stops | | |
| (D) | Start button and electrical values | | |

Automation and Robotics Sample Test Answer Key

| Question | Answer |
|--|--------|
| 1. | D |
| 2.3.4. | D |
| 3. | Α |
| 4. | В |
| 5. 6. 7. | С |
| 6. | C C |
| 7. | С |
| 8. | Α |
| 9. | D |
| 10. | D |
| 11. | D |
| 12. | С |
| 13. | С |